

# Dependent Types for Multirate Faust

Extending the Faust audio programming language for vector and multirate signal processing

## A Vector API for Faust

Vector signals map discrete time to vector values (ordered collections of values). Signal rates are modified by vector manipulation operations.

Operation	Semantics
<code>vectorize</code>	Collects $n$ consecutive samples (the constant value $n$ is provided in the type of the scalar signal that is the second argument) from an input signal and outputs an $n$ -vector signal.
<code>serialize</code>	Maps a signal of $n$ -vectors to the signal of their linearized $n$ elements.
<code>[]</code>	Provides, using as inputs a signal of vectors and one of integer indexes, an output signal of successively indexed vector elements.
<code>#</code>	Builds a signal of concatenated vectors from its two vector signal inputs. The size of the output vectors is the sum of the vector sizes of its arguments.
<code>{}</code>	The empty vector.

## Faust

Faust is a **functional programming language** specifically designed for synchronous real-time signal processing and synthesis. A Faust program describes a signal processor **process** that maps input signals to output signals. The Faust compiler can perform automatic parallelization and produces highly optimized C++ code.

The following top-level **process** signal processor halves its input:

```
process = _,0.5 : * ;
```

where « , » and « : » put two processors in parallel and sequence, while « \_ » denotes the identity signal processor.

## An Example: Haar Filtering

```
down = vectorize(2),1 : [] ;
mean = _ <: _,mem :> _,2 : / ;
left = _,! ;
process = _ <: (mean:down),down <: left,- ;
```

**down**: builds 2-vectors from its input, and picks the second element.  
**mean**: computes the mean of successive elements in its input signal.  
**left**: takes a pair of signals, keeping the first one.  
**process**: copies its input; the first copy is averaged, and both copies are downsampled; the outputs are the average signal and the difference of the downsampled copies.

## Vector Operations as Static Rate Transformers

### Key Insights

- **Dependent type system** based on integer value spans:

$$\text{int}[n, m]$$

- Connection-matching constraints relaxed via **subtyping**:

$$n' \leq n \text{ and } m \leq m' \implies \text{int}[n, m] \subset \text{int}[n', m']$$

- **Sum types** for mixing signals (`:>`):

$$\text{int}[n, m] + \text{int}[n', m'] = \text{int}[n + n', m + m']$$

- **Signal rate algebra** of rational numbers  $f$  in  $\mathbb{Q}(*, /)$

- **Rated signal types**  $t^f$ , grouped in **impedances**  $z$

- **Vector datatype** constructor  $\text{vector}_n(t)^f$

- Vector operations as static **rate transformers**:

Operation	Type
<code>vectorize</code>	$(t^f, \text{int}[n, n]^{f'}) \rightarrow (\text{vector}_n(t)^{f/n})$
<code>serialize</code>	$(\text{vector}_n(t)^f) \rightarrow (t^{f*n})$
<code>[]</code>	$(\text{vector}_n(t)^f, \text{int}[0, n-1]^f) \rightarrow (t^f)$
<code>#</code>	$(\text{vector}_n(t)^f, \text{vector}_m(t)^f) \rightarrow (\text{vector}_{n+m}(t)^f)$
<code>{}</code>	$() \rightarrow (\text{vector}_0(t)^f)$

- Static and dynamic (denotational) semantics consistency

- Signal rate correctness theorem

### Faust Typing and Rating Static Semantics

$$(i) \frac{T(I) = \Lambda l.(z, z') \quad \forall (x, S) \in l \quad l'(x) \in S}{T \vdash I : (z, z')[l'/l]} \quad (:) \frac{T \vdash E_1 : (z_1, z'_1) \quad T \vdash E_2 : (z'_1, z'_2)}{T \vdash E_1 : E_2 : (z_1, z'_2)}$$

$$(<:) \frac{T \vdash E_1 : (z_1, z'_1) \quad T \vdash E_2 : (z_2, z'_2) \quad z'_1 < z_2}{T \vdash E_1 <: E_2 : (z_1, z'_2)} \quad (,) \frac{T \vdash E_1 : (z_1, z'_1) \quad T \vdash E_2 : (z_2, z'_2)}{T \vdash E_1, E_2 : (z_1 || z_2, z'_1 || z'_2)}$$

$$(:>) \frac{T \vdash E_1 : (z_1, z'_1) \quad T \vdash E_2 : (z_2, z'_2) \quad z'_1 > z_2}{T \vdash E_1 :> E_2 : (z_1, z'_2)} \quad (\subset) \frac{T \vdash E : (z, z') \quad z' \subset z'_1 \quad z_1 \subset z}{T \vdash E : (z_1, z'_1)}$$

$$(\sim) \frac{T \vdash E_1 : (z_1, z'_1) \quad T \vdash E_2 : (z_2, z'_2) \quad z_2 = z'_1[1, |z_2|] \quad z'_2 = z_1[1, |z'_2|]}{T \vdash E_1 \sim E_2 : (z_1[|z'_2| + 1, |z_1|], z'_1)}$$